

$$(5.115) \quad \tilde{x}_i = ax_i + b$$

$$(5.116) \quad \tilde{w}_{ji} = \frac{1}{a} w_{ji}$$

$$(5.117) \quad \tilde{w}_{j0} = w_{j0} - \frac{b}{a} \sum_i w_{ji}$$

$$(5.113) \quad z_j = h\left(\sum_i w_{ji} x_i + w_{j0}\right)$$

(5.115), (5.116), (5.117) の変換 π 下 $\tilde{z}_j = z_j$ となる

$$\begin{aligned} \tilde{z}_j &= h\left(\sum_i \tilde{w}_{ji} \tilde{x}_i + \tilde{w}_{j0}\right) \\ &= h\left(\sum_i \tilde{w}_{ji} (ax_i + b) + \tilde{w}_{j0}\right) \\ &= h\left(\sum_i a \tilde{w}_{ji} x_i + \sum_i b \tilde{w}_{ji} + \tilde{w}_{j0}\right) \\ &= h\left(\sum_i w_{ji} x_i + w_{j0}\right) = z_j \end{aligned}$$

同様にして $\tilde{y}_k = y_k$ となる

$$(5.114) \quad y_k = \sum_j w_{kj} z_j + w_{k0}$$

$$\tilde{y}_k = \sum_j w_{kj} \tilde{z}_j + w_{k0} \stackrel{(5.113)}{=} \sum_j w_{kj} z_j + w_{k0} = y_k$$

$$(5.119) \quad \tilde{w}_{kj} = c w_{kj}$$

$$(5.120) \quad \tilde{w}_{k0} = c w_{k0} + d$$

a 変換 π 下

$$(5.118) \quad \tilde{y}_k = c y_k + d \quad \text{と対応: } z_j \text{ となる}$$

$$\begin{aligned} \tilde{y}_k &= \sum_j \tilde{w}_{kj} z_j + \tilde{w}_{k0} = \sum_j c w_{kj} z_j + c w_{k0} + d \\ &= c \left(\sum_j w_{kj} z_j + w_{k0}\right) + d \\ &= c y_k + d \end{aligned}$$